IN THE SPECIFICATION:

Please amend paragraphs [0017] and [0052] in the specification as follows.

[0017] An imaging device (1a) ~~has an image blur compensation means (20) for compensating a blur of an image to be inputted to an imaging sensor (4) via an imaging optical system (L) and~~ is operable to shoot in a consecutive shooting mode in which a plurality of frames (Ia and Ib) of the image are consecutively shot through one operation of a shutter operation section (36) and shot image signals are generated, the imaging device comprising: image blur compensation means for compensating a blur of an image; operation means (39 and 40) for setting the consecutive mode; recording means (12) for recording the plurality of the consecutively shot frames (Ia and Ib) of the image; and display means (55) for displaying the frames of the shot image, wherein when the consecutive shooting mode is set by the operation means (39 and 40), in response to the one operation of the shutter operation section, shooting with compensation of the blur of the image and shooting without the compensation are consecutively performed ~~shooting with and without compensation, on the image to be inputted to the imaging sensor (4), using the image blur compensation means (20) is consecutively performed and the plurality of the shot frames of the image can be displayed on the display means (48 and 55)~~.

[0052] The microcomputer 3 obtains a drive-control amount (control signal) for the L2 lens unit, which is required for motion compensation, by performing filtering, integral processing, phase compensation, gain adjustment, clip processing and the like for the outputted signal provided from the angular velocity sensors 18x and 18y via the A/D conversion sections 19x and 19y.

The obtained control signal is outputted via the D/A conversion sections 17x and 17y to the yawing drive control section 14x and the pitching drive control section 14y. In other words, the yawing drive control section 14x and the pitching drive control section 14y drives the L2 lens unit based on the control signal, thereby performing compensation of the image ~~compensating a motion of the image caused by the motion of the digital camera 1a~~.